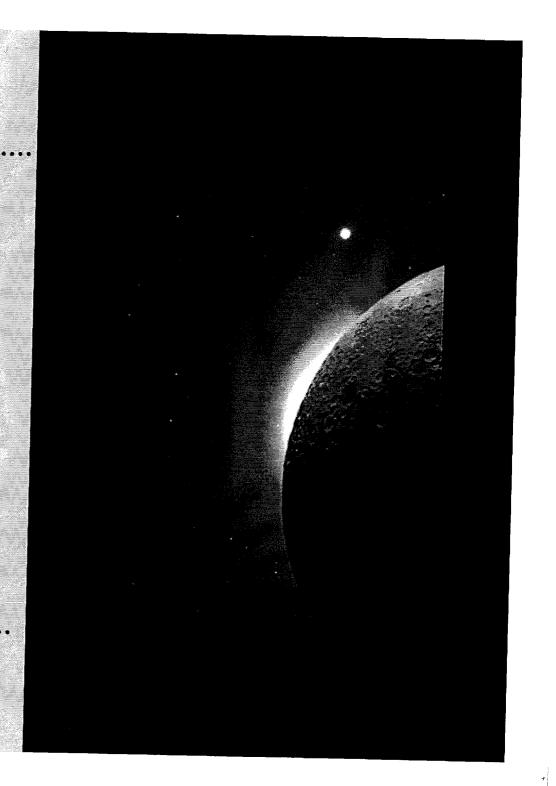
Role of Small Spacecraft in Planetary and Space Exploration

Charles Elachi
JPL / Caltech

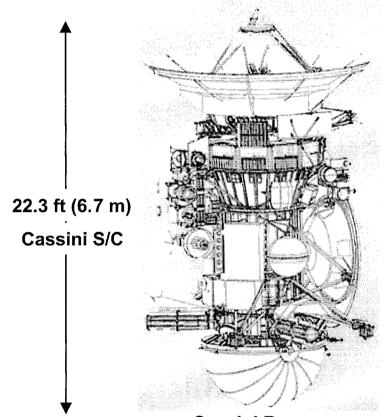
August 22, 2000



JPL 0 0 14th AIAA / USU CONFERENCE ON SMALL SATELLITES

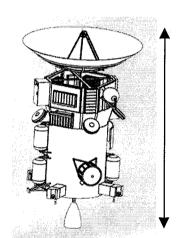






Miniaturization

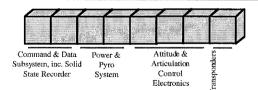
Modern long-life, highly-reliable spacecraft: X2000 contribution

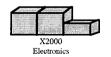


11.4 ft (3.5 m)
Europa Orbiter S/C

Cassini Bays

X2000 First Delivery Chassis

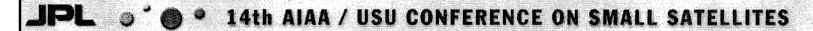




	CDS, inc.		AACS		Packaging/			X2000
100000000000000000000000000000000000000	SSR	PPS	Electronics	Transponders	Structure	Total		Electronics
MASS	59.2	45.4	20.9	18.3	54.1	198.0	ATTEMPT, NEW	56 kg
POWER	69.0	36.7	31.4	17.3	0.0	154.4		120 W
VOLUME	0.072	0.072	0.108	0.036	N/A	0.288		0.074

Plus Shielding (28 kg) Orbit insertion cubic meters

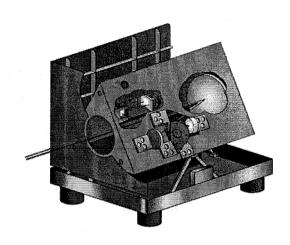
14th AIAA / USU CONFERENCE ON SMALL SATELLITES Micro-Inertial Reference System (µIRS) Conventional gyro technologies **MEMS** micro-gyro 10 deg/hr 1 < 0.01 Cost 1000 100 Weight lbs 100 10 0.1 0.01 Volume cubic inches 1000 100 10 0.1



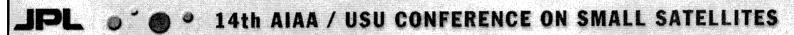




DS1 Miniature Integrated Camera-Spectrometer (MICAS)



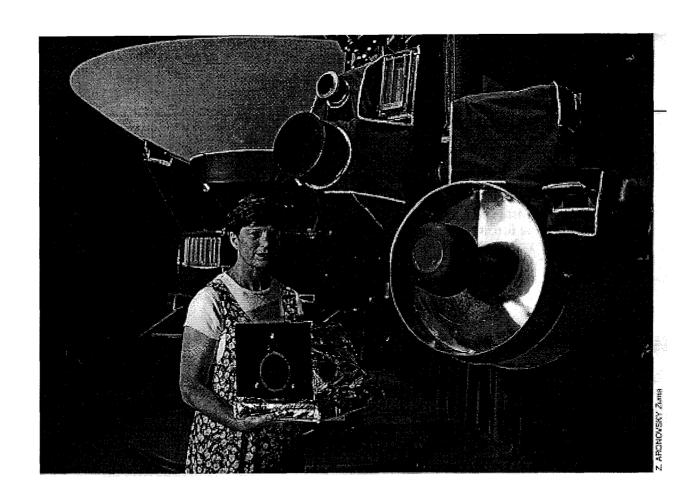
Resource	<u>Today's</u>	<u>Historical</u>	<u>MICAS</u>
	Constraints	<u>Average</u>	
Mass (kg)	< 10	~100	7
Power (W)	< 10	~100	6
Cost (\$M)	< 30	~100	< 15







MICAS Compared to the Voyager Remote Sensing Instrument Suite

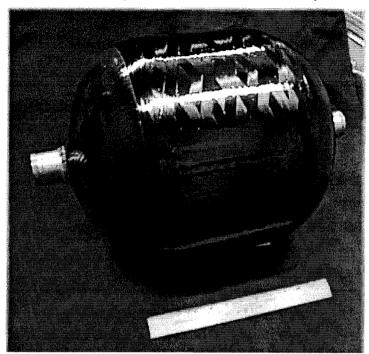


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Ultralight Linerless Composite Pressure Vessels and Conformal Tanks

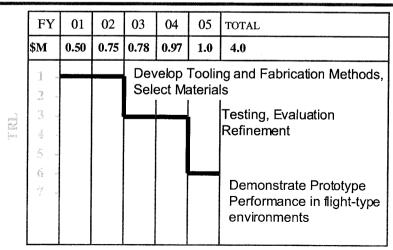


PRODUCTS

- Ultralight linerless composite pressure vessels for storing propellants for spacecraft
 - Next generation technology for Propellant and pressurant tanks
 - PV/W up to 3,500,000 for propellant tanks, 7,500,000 for pressurant tanks
- Ultralight toroidal (and/or other shapes) composite tanks for storing propellants for spacecraft
 - Allows propellant and pressurant tanks to be more compact and space efficient
 - Provides the capability to fit tanks in nonstandard spacecraft bus configurations easily

Performance Metrics

<u>Metric</u>	<u>SOA</u>	Goal
Mass	1	0.25
Cost	1	0.25
Volumetric Eff.	1	0.5
Development Time	1	0.6



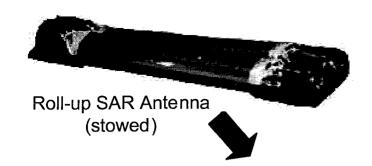
5/18/00





Roll-up Inflatable Membrane SAR Antenna

Characteristics



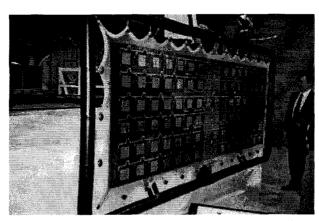
- Roll-up SAR Antenna (partially deployed)

- · Roll-up inflatable planar frame structure
- Inflatable/rigidizable reinforced aluminum laminate boom
- 3 layers of stretched membrane to form RF aperture (5 micron copper on 2 mil Kapton)
- T/R module distributed on central support for 1-D scanning
- · Frequency: 1.25 GHz; Bandwidth: 80 MHz
- Polarization: dual linear
- · Gain:26.7 dB; Efficiency: 74%
- < 2kg/m² mass density



Benefits

- Mass reduction from 23 kg/m² to 2 kg/m²
- High reliability deployment
- · High packaging efficiency/small launch vehicle
- Low production cost
- · Applicable to most SAR missions
- Scalable to other frequencies up to Ka-band

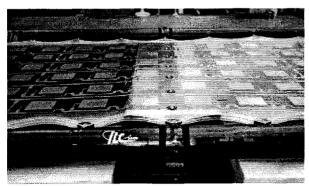


Roll-up SAR Antenna (deployed)





Membrane Compatible T/R Module



Inflatable membrane antenna



Flexible T/R Module

Characteristics:

- MEMS device fabrication on flexible Si
- MEMS micro heat pipes
- High-efficiency Class-E SSPA
- · Fiber-optics embedded in membrane



Benefits:

- High efficiency T/R with local thermal management
- Low-cost manufacturing process
- · Agile 2-D beam scanning
- Phase correction

New Capabilities:

- · High-resolution, wide-swath
- Rapid response
- Digital beamforming
- Very large apertures

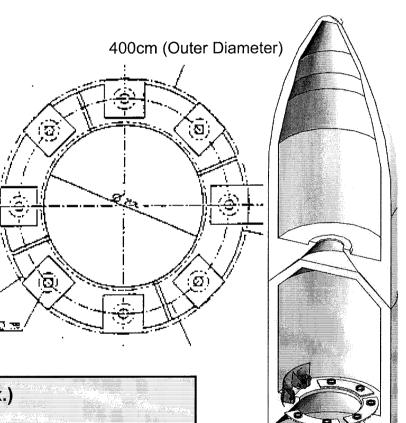
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ASAP5 Configuration

Micromission S/C is compatible with Ariane-5 dual/triple primary payload configurations (SPELTRA and SILDA5)



Micro-satellite (8 max.)

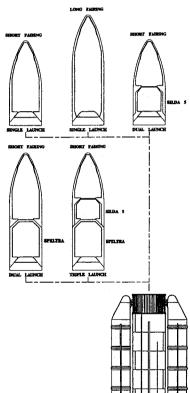
- Mass: 120 kg

- Volume: 60cm * 60cm x 71cm (h)

Twin/Banana Micro-satellites (4 max.)

- Mass: 240 kg

- Volume: 60cm(r) * 71cm (h) * 80 degrees



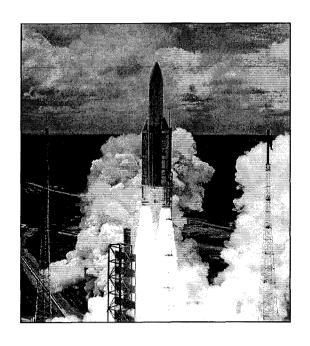
ARIANE 5 Payload Compartment Configurations





Ariane/ASAP Piggybacks

Ariane Structure for Auxiliary Payloads (ASAP) provides a standardized low-cost launch of secondary payloads



- ☐ Low marginal launch cost
- □ 3-Months launch period allows launching with commercial GTO missions (6-8 opportunities/year)
- ☐ Approx. 90% of all Ariane launches are to GTO
- ☐ Transparent to the primary passenger manifest directly with Arianespace
- ☐ Powered off during launch countdown and launch
- ☐ User's Manuals available for ASAP4 and ASAP5
- ☐ Six Ariane-4 ASAP launches to date (21 payloads)
- ☐ First Ariane-5 ASAP launch in Sep/Oct 2000

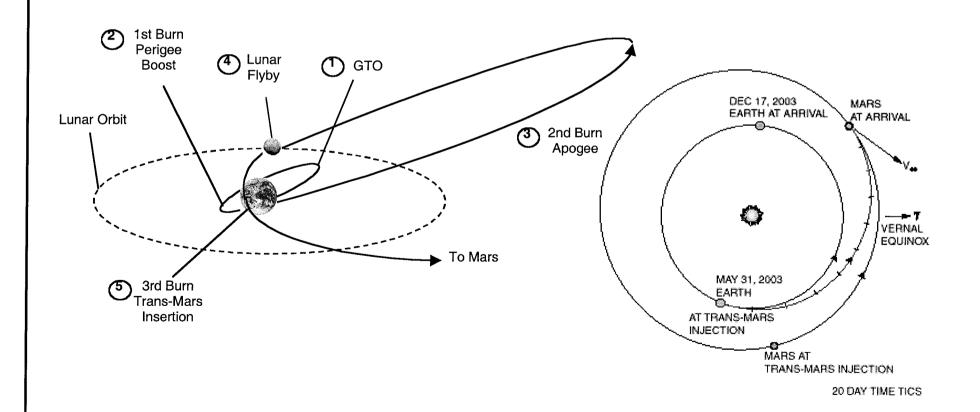






From GTO to Mars

The multi-burn Earth/Lunar flyby strategy allows launch periods of at least 3 Months





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Estimated Payload Capability

Destination	Launch Year	Payload to Approach (kg)	Payload to Orbit (kg)
Mars	2003	45	10
	2005	45 – 50	10 – 15
	2007	50 – 60	15 – 20
Venus	2002	35 – 45	5 – 10
	2004	45 – 55	5 – 10
	2005	50 – 60	10 – 15
	2007	55 – 65	15 – 20
Mercury	2002	15 – 25	None
	2004	5-15	None
	2005	10 – 20	None
Main Belt Asteroids	Same As Venus	35 – 60	None
Near-Earth Asteroids	Any	60 - 70	None
Moon	Any	90 – 100	40 – 60

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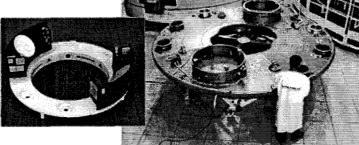


Micromission launch on Ariane-5









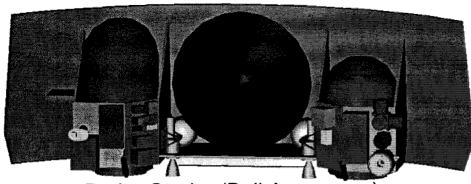


Dual
Primary
GTO
Comsat
Payloads

Common S/C design for probe carrier and science orbiters (240 kg each)

Ariane-5 Structure for Auxiliary Payloads (ASAP5)

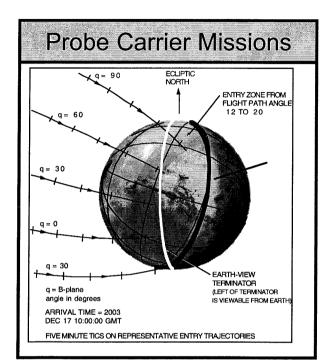


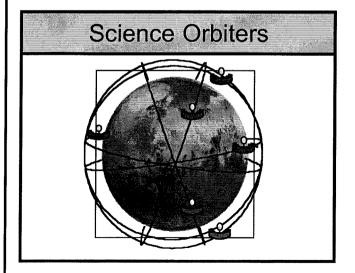


Probe Carrier (Ball Aerospace)

- □ ASAP5 secondary launch to GTO
- □ 3 month launch period
- ☐ 40-60 kg probes to Mars
- ☐ 6-20 kg instruments in Mars Orbit
- NASA-CNES cooperation

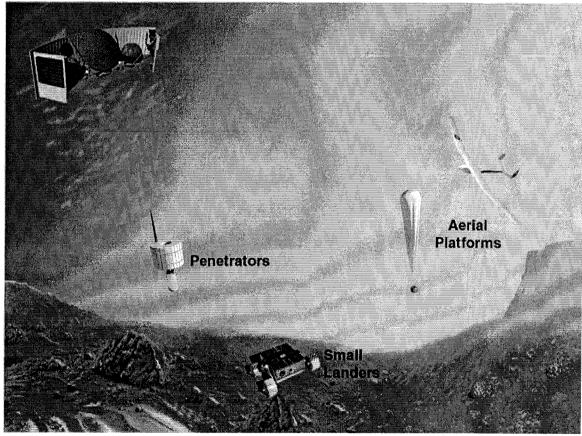






Mars Micromission Examples

Small stand alone Mars mission doing focused science mission from orbit or in situ.







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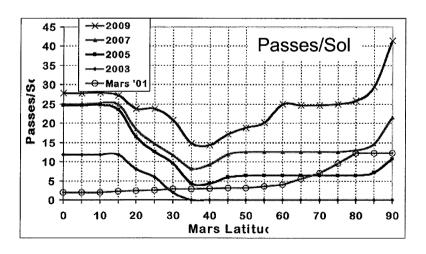


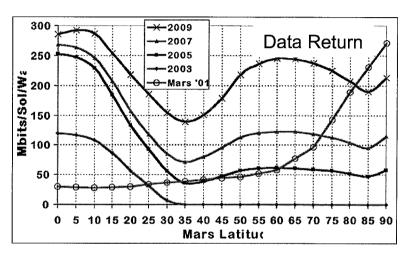
Microsatellite Constellation

Telecom Performance Evolution Summary

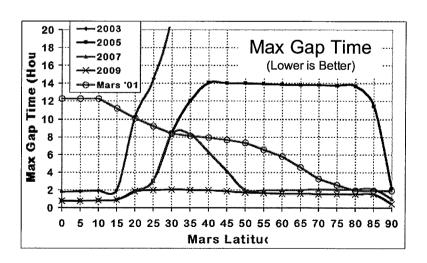
Inject	June '03	Aug '05	Sept '07	Oct '09
MOI	Dec '03	June '06	April '08	June '10
Finish Aerobrake	May '04	Nov '06	Sept '08	Nov '10
ASAP 1 ASAP 2 ASAP 3 ASAP 4 ASAP 5 ASAP 6 ASAP 7	172 , 800km	172, 800km 172, 800km 171, 800km	172, 800km 111, 800km 111, 800km 172, 800km	172, 800km 111, 800km 111, 800km 172, 800km 111, 800km 111, 800km

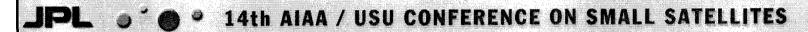
SOAP Generated Assumes 15° Minimum Elevation Angle





Assumes omni antenna on both ends of the link

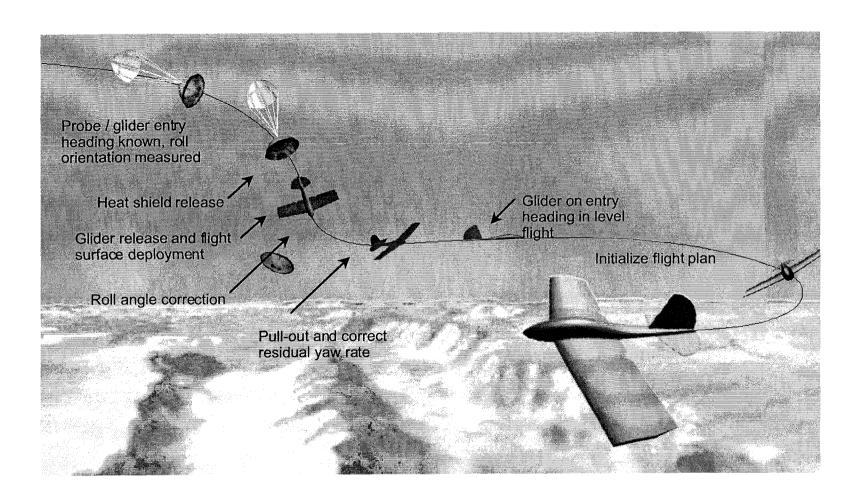








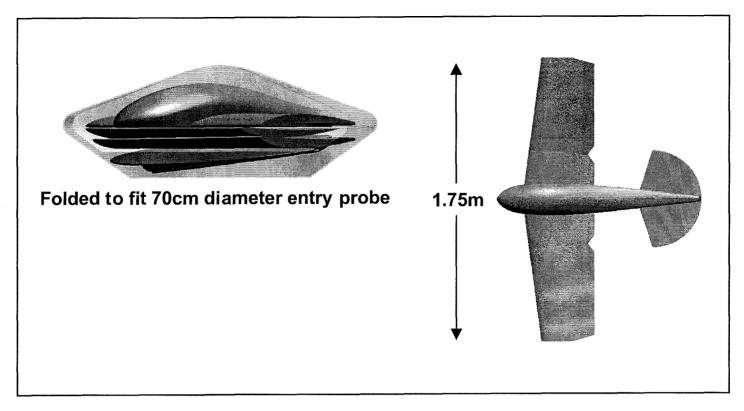
Glider Deployment







Airplane Overview Glider layout

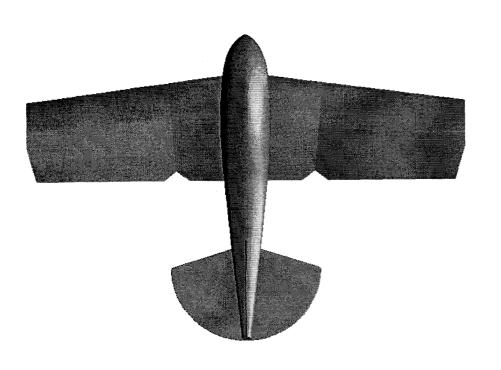


V AeroVironment,

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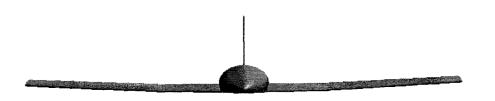


Concept Glider Configuration



Baseline	Geometry	8
Performa	nce	

Wing Span	1.75 m
Wing Area	0.60 m^2
Mean Chord	0.343 m
Aspect Ratio	5.1
Structural Wt.	2.0 kg
Gross Wt. + Reserve	8.5 kg
Flight Speed @ 5km Alt.	108.0 m/s
Sink Rate @ 5km Alt.	12.7 m/s
Mach No. @ 5km Alt.	0.47
Reynolds No. @ 5km Alt.	40,000
Design Lift Coef.	0.90
Max. Lift Coef.	1.25
Turning Radius @ 30 deg bank	7 km
Glide Ratio	8.5 : 1



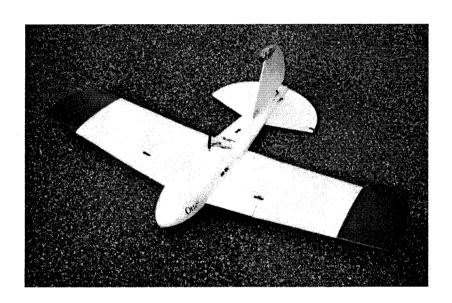


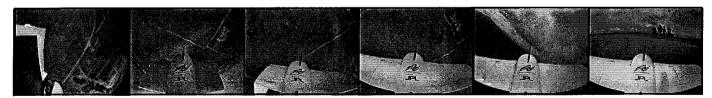


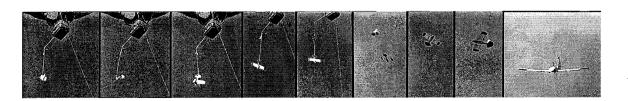




Glider







Sponsored by:







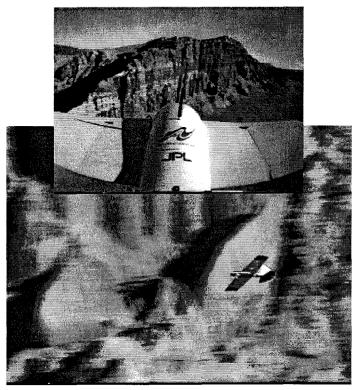
Mars Aircraft/Glider Science

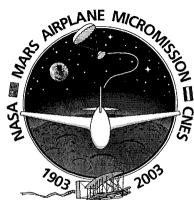
- High-resolution surface imaging Landing site selection/sample return

 - Rover navigation
 - Geology/geomorphology/exobiology
- Compositional mapping Surface mineralogy

 - Aqueous deposits
- Neutron spectroscopy/radar sounding Search for water
- Electromagnetics/Paleomagnetics Search for water

 - Magnetic anomalies
- □ Atmospheric measurements
 - Temperature, pressure, mass and energy transport
 - Atmospheric composition
 - Dust



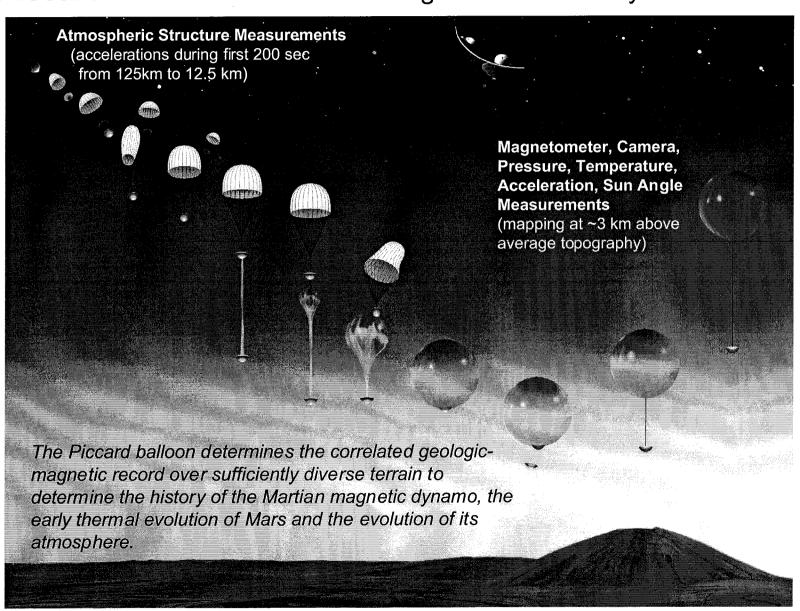


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Piccard: A Mars Balloon-borne magnetometer survey micromission





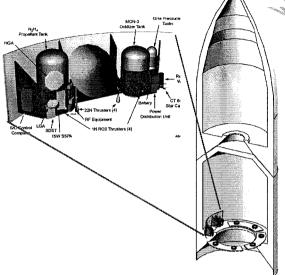
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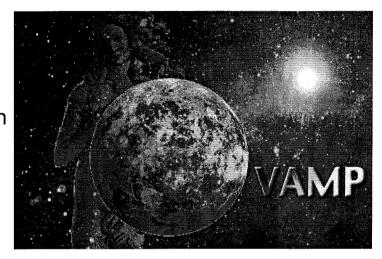




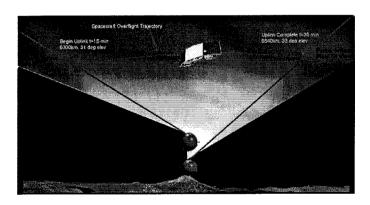
Venus Atmosphere Measurement Probe

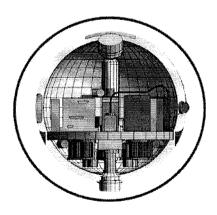


The VAMP mission plans a piggyback launch on an Ariane 5 ...



and upon arrival at Venus, the spacecraft will release a probe, receive atmospheric science telemetry from the probe and send the data back to Earth.











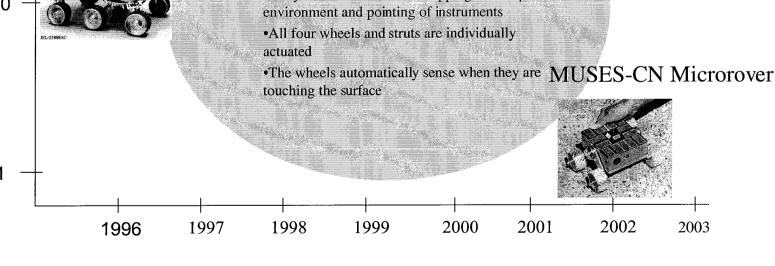








14th AIAA / USU CONFERENCE ON SMALL SATELLITES Microrover Comparison Athena **MUSES-CN** Capabilities 100 •Camera with integral laser ranging, 9-position Sojourner filter wheel, 3 focus positions 3 resolutions; 0.08,2.5 and 8.5 mm •Near IR spectrometer giving <10 nm spectral kg resolution, 0.8-1.7 micron band •Sojourner-Like Alpha X Ray Spectrometer •Body articulation allows "hopping" in $\sim 10 \mu G$ 10

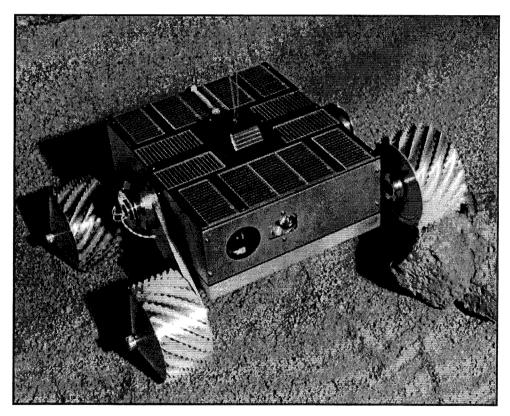






MUSES CN Rover

- 256x1 InGaAs detector array giving <10 nm resolution over 0.8-1.7 micron band; RMS noise < 2% of full scale
- panoramic imaging using a 256x256 detector at 1 mrad/pixel in 9 vis/VNIR spectral bands,
- 3 focus positions/resolutions:
 - 6 m, 8.5 mm
 - 2 m, 2.5 mm
 - .07m, .08mm
- Sojourner Like AXS
- body articulation allows "hopping" in ~10µG environment and "posing" of instrument
- Mass 1300 grams
- Size 14 x 14 x 6 cm
- Power Capability 2.3 W (normal incidence)
- Max. velocity,
 - rolling contact, 1.5 mm/s
 - hopping or skimming 10 cm/s
- Data rate 4800 bits per second [20km range]



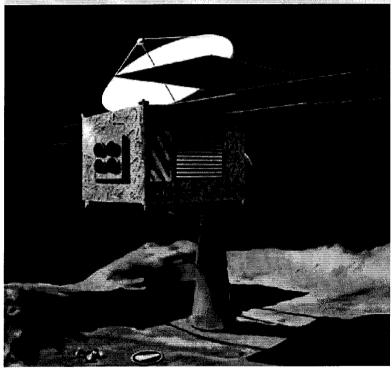
four 6.5cm dia wheels on 7 cm articulated struts





MUSES CN Project Overview

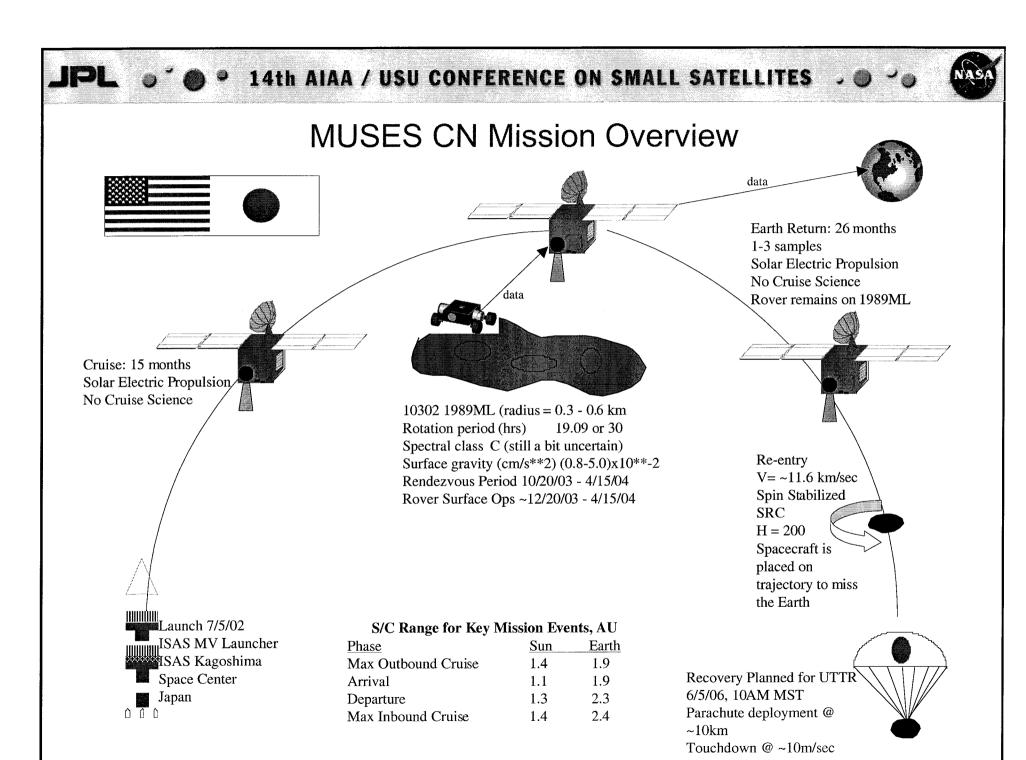
MUSES C spacecraft landing on the asteroid. MUSES CN rover in foreground.

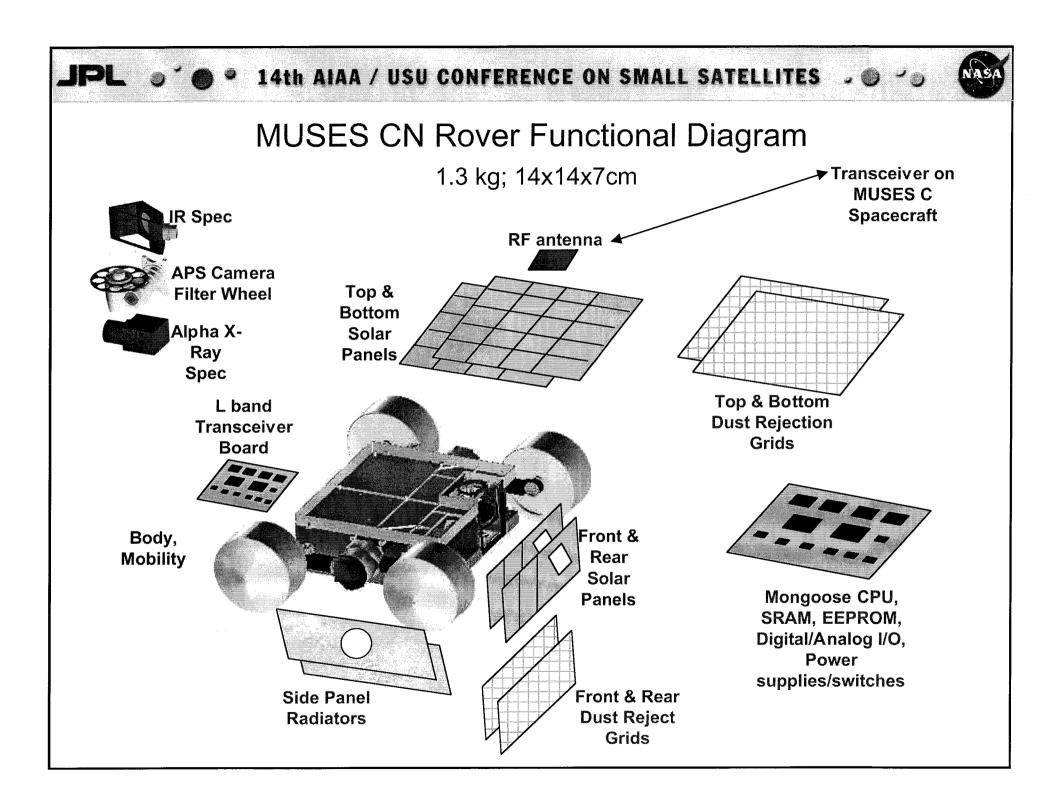


- Introduction: MUSES CN is the project which will implement the NASA portion of the NASA-ISAS collaboration on the ISAS MUSES C Asteroid Sample Return Mission
- Objectives: 1) develop and demonstrate the rover technology for asteroid mobility and ultraminiaturization beyond Sojourner and 2) acquire scientific data, both remote sensing and in situ, from one of the many near Earth asteroids including a sample of the surface.
- Scope of Work: 1) rover development/delivery,
 2) support for science teams, 3) rover and science teams ops at the asteroid, 4) DSN tracking of MUSES C, 5) navigation support for MUSES C, 6) support for ISAS testing @ ARC and 7) recovery of MUSES C sample capsule in US territory.

Schedule:

FY 97 F	Y 98 [Development	FY 02	Operations	FY 06
Huntress/Nis		CDR Rover Delivery	to Launch	Rendezvous	Sample
Meeting 5/2		9 ISAS 8/01	7/02	10/03	Recovery 6/06







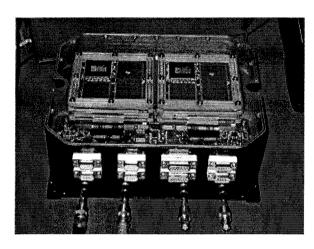


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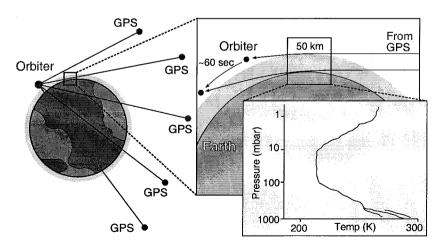




The BlackJack Scientific GPS Flight Receiver



The BlackJack: 20 x 20 x 9 cm



GPS Atmospheric Limb Sounding

Key Features:

- 48 Parallel tracking channels
- Four L1/L2 antenna inputs
- Sub-millimeter phase precision
- · Modular hardware and software
- Enhanced codeless operation
- · Low cost fault-tolerant design

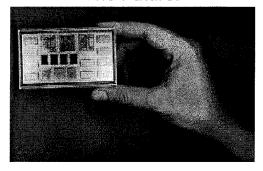


Principal Applications:

- Centimeter orbit determination
- Gravitational field mapping
- Atmospheric limb sounding
- Ionospheric imaging
- Bistatic ocean altimetry



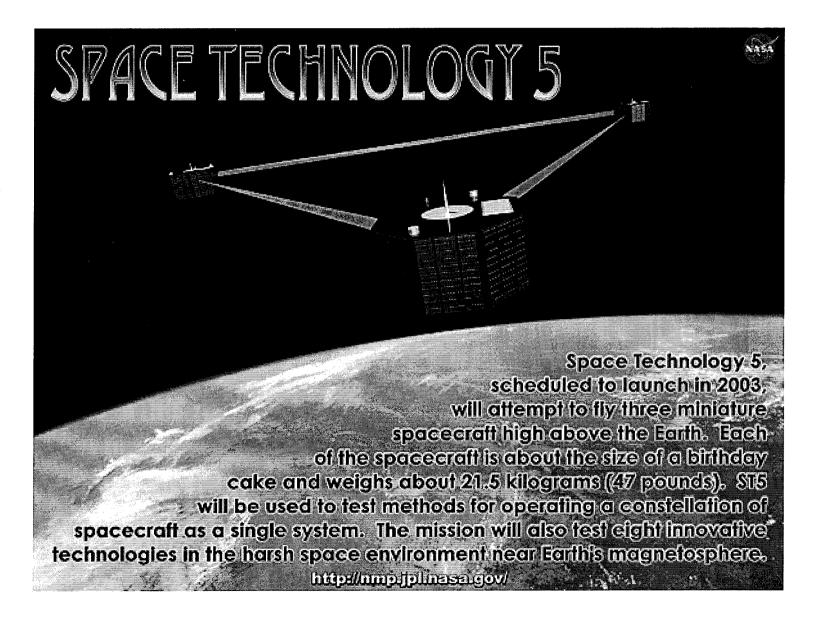
The Future:



"GPS on a Chip"







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Space Technology 5

Nanosat Constellation Trailblazer Mission

Miniature Spacecraft

 Systems Design Integration and Test Technologies

Candidate Spacecraft Technologies

- 5V bus 1/4V logic
- Li-Ion batteries
- Miniature transponder
- Miniature Thrusters
- Multi-functional structure
- Variable emittance coatings

Constellation Control,
Coordination, and Operations
Architecture

- Ground system autonomy
- Relative ranging
- Intra-constellation communications

Constellation Class Missions
Simultaneous, Multipoint, InSitu Characterization of the
Magnetosphere



Single Nanosats & Probes
Reduced Risk Small
Spacecraft Bus for Low Cost Missions

Virtual Platforms
For Science Missions

TECHNOLOGY



VALIDATION

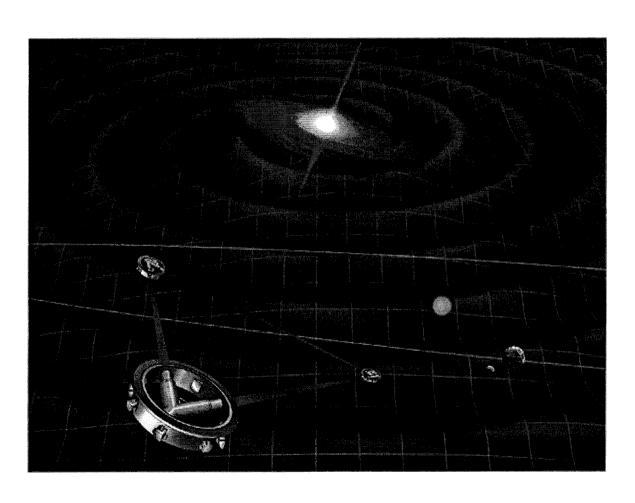
5.6 R_e



INFUSION



Laser Interferometer Space Antenna (LISA)



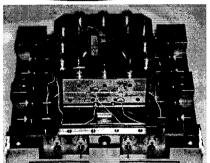


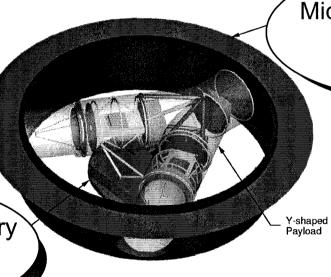


LISA **Technology Drivers**

Inertial sensors Noise $< 10^{-16} \, g$ rms for 1000 s average



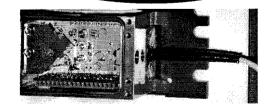


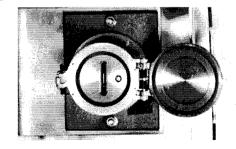


Micronewton thrusters Range 1-100 µN Noise <1 μN

Picometer interferometry Accuracy < 1 pm rms for 1000 s average

1 W laser





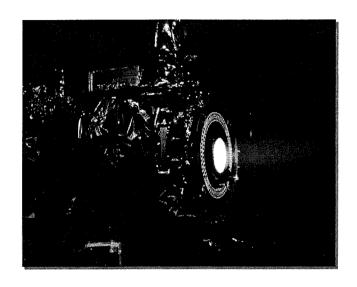


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Ion Propulsion System (IPS)



Description

Single-fault-tolerant, multi-engine Ion Propulsion System with significantly enhanced throughput capability and improved electronics packaging/thermal performance

Criticality

CNSR mission enabling. Current DS1 implementation of ion propulsion incurs unacceptable mass, performance, and thermal management penalties for CNSR.

Status

Major development effort initiated. Trade study identified the technology development path which provides the greatest mission benefit for the least development risk and cost.

Requirements

Increase engine throughput to > 2X NSTAR design point

Reduce system dry mass and cost Develop a single-fault-tolerant system architecture

- higher reliability and fewer parts than ST4
- improved spacecraft packaging and thermal management

Develop system architecture flexible enough to be used by other SEP missions

Development Path

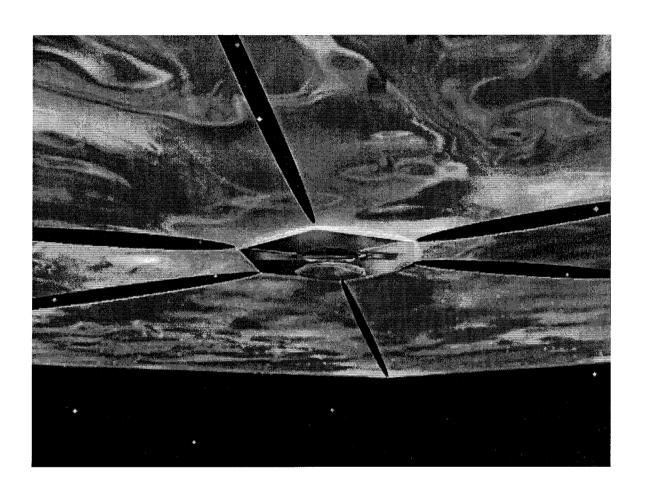
Initial Trade Space			
Engine Engine System			
Power	Throughput	Architecture	Working Design
2.3 kW (NSTAR)	80 kg	Conventional (one	• 3.1 kW Enhanced NSTAR
3.1 kW (enhanced NSTAR)	180 kg	PPU operates one	Engine Engine
5.0 kW (new engine)	275 kg	engine)	- 400 kM/ vaman
		Centralized High-	voltage and neutralizer
		Voltage and	functions
		Neutralizer Functions	







Propellantless Propulsion

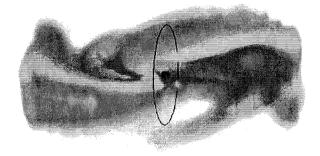


Solar Sailing





Solar Polar Imager

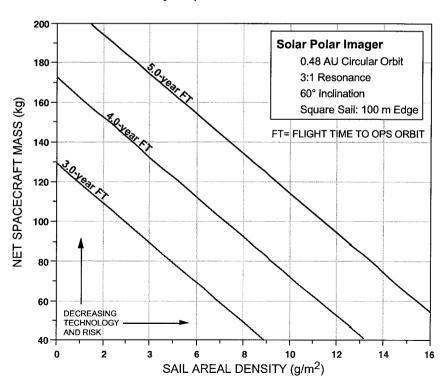


Technology Implications

- Flight System Mass
 - Lower spacecraft mass allows faster flight times for fixed sail technology (maturity)
 - Lower spacecraft mass allows for reduced sail technology and risk for fixed flight time
- Project Cost
 - Lower spacecraft masses may allow for consideration of cheaper launch vehicles

Mission Description

- Example Mission Design
 - Launch: Taurus w/ Up.-Stg or Small Delta II (C₃ = 0 km²/s²)
 - Solar Sail Trajectory
 - * 4-5 Year Flight Time, 2 year OPS
 - Final Orbit: 0.48 AU Solar Orbit with 60° Inclination
 - * 3:1 Resonance with Earth
- Flight System Concept
 - 3-Axis or Spin-Stabilized Platform
 - Solar Array Implementation

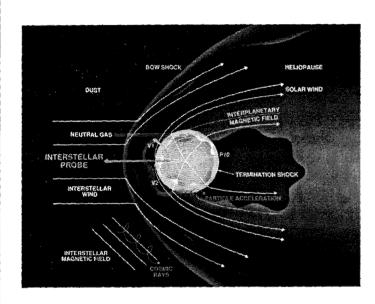


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Interstellar Probe Spacecraft Mass & Solar Sail Challenge



Technology

- Solar Sail: < 1 g/m ², 200 m raduis
- DSN 70m Subnet w/ Ka-band Uplink
- Next Generation ARPS
- · Next Generation System On A Chip
- Ka-band S/C Components and Phased Array
- Hot-Gas Propulsion
- · Micro-S/C Technology
- Low Mass/Power Instrumentation

Science Objectives

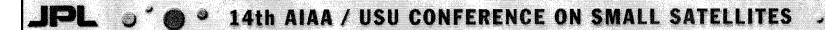
- Explore the interstellar medium and determine directly the properties of the interstellar gas, the interstellar magnetic field, low energy cosmic rays, and interstellar dust
- Determine the structure and dynamics of the heliosphere, as an example of the interaction of a star with its environment
- Study, in situ, the structure of the solar wind termination shock, and the acceleration of pickup ions and other species
- Investigate the origin and distribution of solar system matter beyond the orbit of Neptune

Mission Description

- Example Mission Design
 - Delta II 7425 Launch (719 kg Cap., $C_3=0 \text{ km}^2/\text{ s}^2$)
 - Flight System Launch Mass: 564 kg
 - Solar Sail Trajectory Targeted for Nose of Heliosphere
 - * 0.25 AU Solar Pass, 200 AU in 15 years
- Flight System Concept
 - "Flying Antenna" Design Implementation (191 kg)
 - Sized for 30 year Operations
 - Payload: Fields & Particles + Imaging

Measurement Strategy

- Measure, in situ, the properties and composition of interstellar plasma and neutrals, low energy cosmic rays, and interstellar dust
- Determine the structure and dynamics of the heliosphere with in situ measurements and global imaging
- Map the infrared emission of the zodiacal dust cloud, measure in situ the distribution of interplanetary dust, and determine the radial distribution of small Kuiper Belt objects







Probing Interstellar Space Miniaturization Effect on Flight Time



